Regional Climate Modeling { A Land Surface Modeling Perspective

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The Model

$$p^{t}$$

$$\downarrow$$

$$x^{t} \rightarrow M \rightarrow x^{t+1}$$

x^t: state variables at time t (e.g., temperature)
p^t: parameters/forcing at time t (e.g., leaf refl.)
M : the model
x^{t+1}: state variables at time t+1

The Model

$p^{t} \qquad p^{T-1}$ $\downarrow \qquad \downarrow \qquad \downarrow$ $x^{t} \rightarrow M \rightarrow x^{t+1} \cdots x^{T-1} \rightarrow M \rightarrow x$

x^T: state variables at final time T p^{T-1}: parameters/forcing at time T-1

The Model

$p^{0} \qquad p^{t} \qquad p^{T-1}$ $\downarrow \qquad \downarrow \qquad \downarrow \qquad \downarrow$ $x^{0} \rightarrow M \rightarrow x^{1} \cdots x^{t} \rightarrow M \rightarrow x^{t+1} \cdots x^{T-1} \rightarrow M \rightarrow x$

x⁰: state variables at initial time
p⁰: parameters/forcing at initial time
M : the model
x¹: state variables at time 1

The Model with uncertainty

$$p^{0}+\varepsilon_{p} \qquad p^{t}+\varepsilon_{p} \qquad p^{T-1}+\varepsilon_{p}$$

$$\downarrow \qquad \downarrow \qquad \downarrow \qquad \downarrow$$

$$x^{0} \rightarrow M \rightarrow x^{1} \cdots x^{t} \rightarrow M \rightarrow x^{t+1} \cdots x^{T-1} \rightarrow M \rightarrow x^{T}$$

$$+\varepsilon_{M} \qquad +\varepsilon_{M} \qquad +\varepsilon_{M}$$

 ε_x : initial state uncertainty ε_M : model uncertainty ε_p : parameter/forcing uncertainty x^t : state variables with accumulated uncertainty

The Earth System Model

$$\partial_t U + (\nabla \cdot \mathbf{V}u)_\eta + \mu_d \alpha \partial_x p + (\alpha/\alpha_d) \partial_\eta p \partial_x \phi = F_U$$

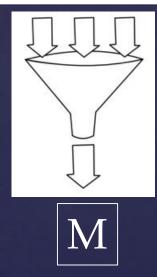
$$\partial_t V + (\nabla \cdot \mathbf{V}v)_\eta + \mu_d \alpha \partial_y p + (\alpha/\alpha_d) \partial_\eta p \partial_y \phi = F_V$$

$$\partial_t W + (\nabla \cdot \mathbf{V}w)_\eta - g[(\alpha/\alpha_d) \partial_\eta p - \mu_d] = F_W$$

$$\partial_t \Theta + (\nabla \cdot \mathbf{V}\theta)_\eta = F_\Theta$$

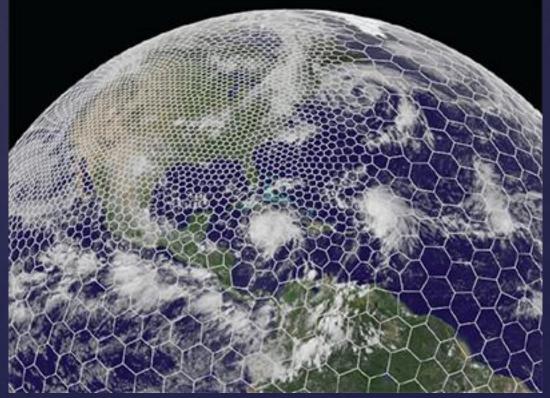
$$\partial_t \phi + \mu_d^{-1}[(\mathbf{V} \cdot \nabla \phi)_\eta - gW] = 0$$

$$\partial_t Q_m + (\mathbf{V} \cdot \nabla q_m)_\eta = F_{Q_m}$$



Model Flavors

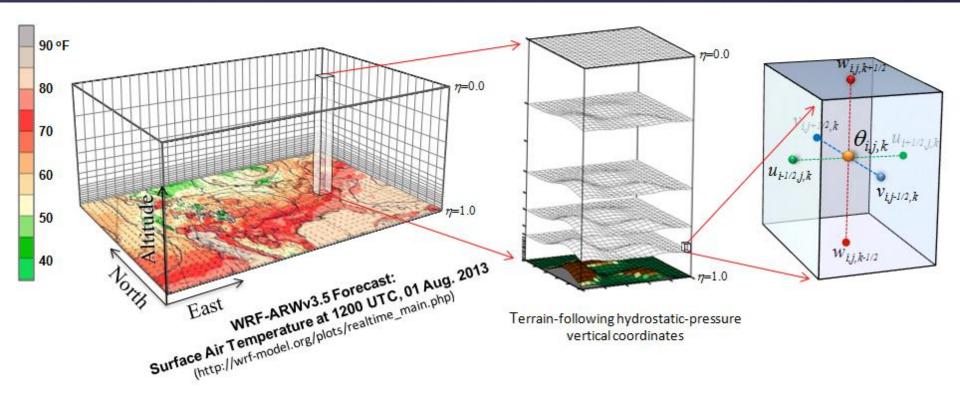
- Operational models typically come in two sizes:
 global (NCAR CESM; NOAA GFS/CFS; ECMWF; etc.)
- Relatively low spatial resolution (~25 50km)
- Used to predict climate (seasonal to decadal) and medium range weather (~10days)



NCAR MPAS model using stretched grid

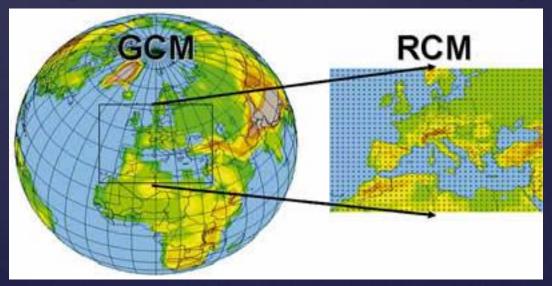
Model Flavors

Operational models typically come in two sizes: regional (NCAR WRF; NOAA NAM/RUC/HRRR) Relatively high spatial resolution (~1km) Used to predict weather and "downscale" climate models NCAR WRF model



Global vs. Regional

- Global models have no lateral boundaries they stretch around the planet
- Regional or limited-area models are spatial subsets of the planet – the easiest method for execution is to embed them in global models
- Why do regional climate modeling?
 - Increased spatial and temporal scales, output products



Dynamical vs. Statistical

- Dynamical models: physics-based models that may or may not have components inspired by statistics
- Statistical models: statistics-based models that may or may not be inspired by physics

$$\partial_t U + (\nabla \cdot \mathbf{V}u)_\eta + \mu_d \alpha \partial_x p + (\alpha/\alpha_d) \partial_\eta p \partial_x \phi = F_U$$

$$\partial_t V + (\nabla \cdot \mathbf{V}v)_\eta + \mu_d \alpha \partial_y p + (\alpha/\alpha_d) \partial_\eta p \partial_y \phi = F_V$$

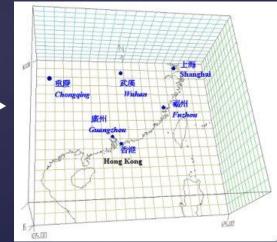
$$\partial_t W + (\nabla \cdot \mathbf{V}w)_\eta - g[(\alpha/\alpha_d) \partial_\eta p - \mu_d] = F_W$$

$$\partial_t \Theta + (\nabla \cdot \mathbf{V}\theta)_\eta = F_\Theta$$

$$\partial_t \mu_d + (\nabla \cdot \mathbf{V})_\eta = 0$$

$$\partial_t \phi + \mu_d^{-1}[(\mathbf{V} \cdot \nabla \phi)_\eta - gW] = 0$$

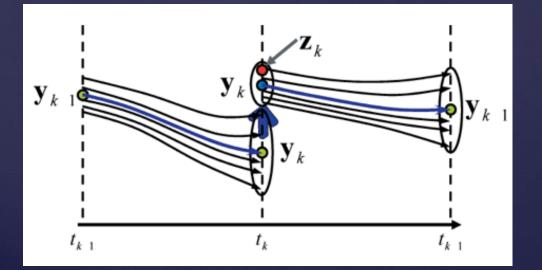
$$\partial_t Q_m + (\mathbf{V} \cdot \nabla q_m)_\eta = F_{Q_m}$$



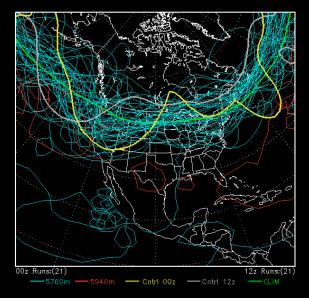
When physics-based models fail, it is not the fault of the physics, but the application of the physics or the statistics

Ensemble Models

- Model results spread due to initialization, parameter and model uncertainty
- Done by many operational centers to create probability forecasts

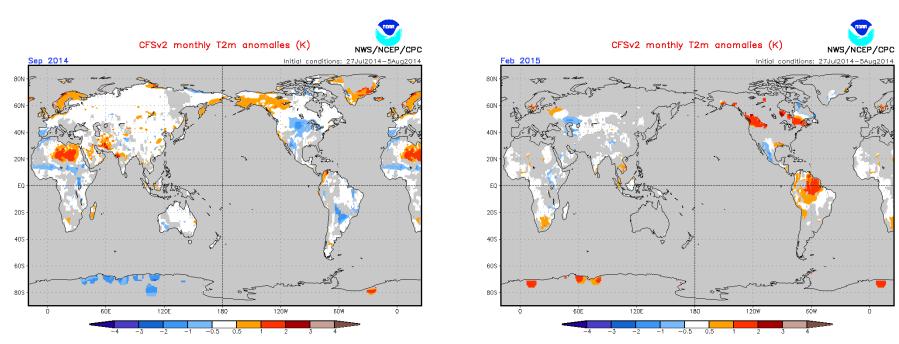






Ensemble Models

- Operation Climate Forecast System at NCEP uses a staggered initialization to produce an ensemble forecast (10-day lags)
- Shading implies lack of skill in the forecast



(Areas of expected skill less than 0.3 are shaded in grey.)

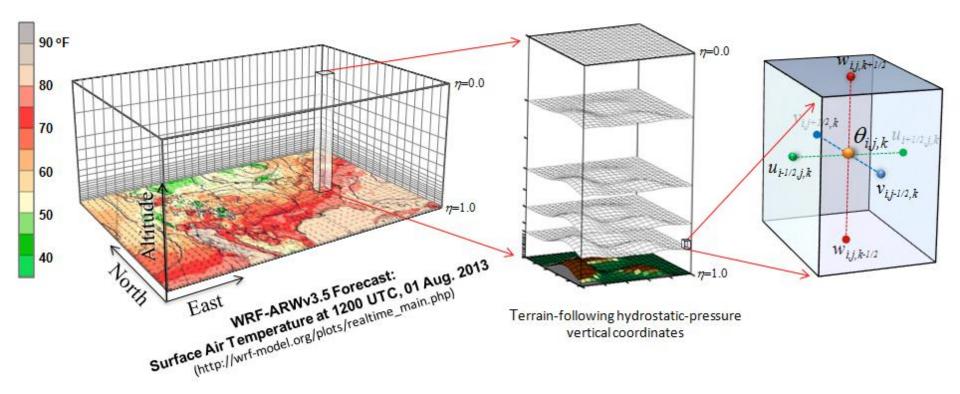
(Areas of expected skill less than 0.3 are shaded in grey.)

The Model Grid: Why a grid?

$$\frac{dT}{dz} = \frac{T(z_2) - T(z_1)}{z_2 - z_1}$$

Discretization of the equations that solve for the future Challenge: initialization

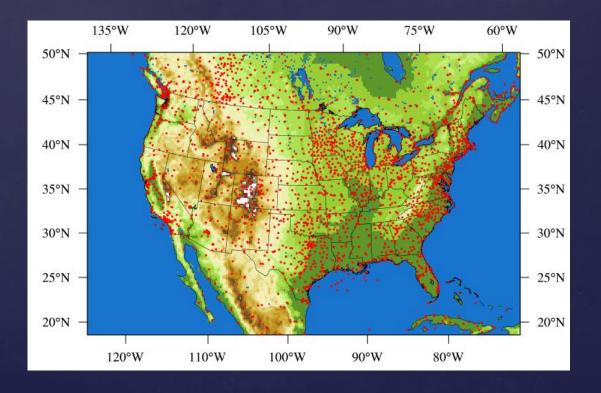
NCAR WRF model



Initialization Uncertainty

• Initialization is usually done with

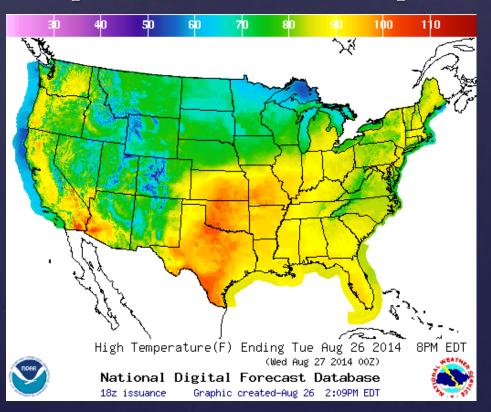
- Observations
- Previous model output
- A blending of observations and model output
- Here is an example of surface reporting stations



Initialization Uncertainty

• Initialization is usually done with

- Observations
- Previous model output
- A blending of observations and model output
- Here is an example of near-surface temperature



Where is the most variation?

Initialization Uncertainty

• Initialization is usually done with

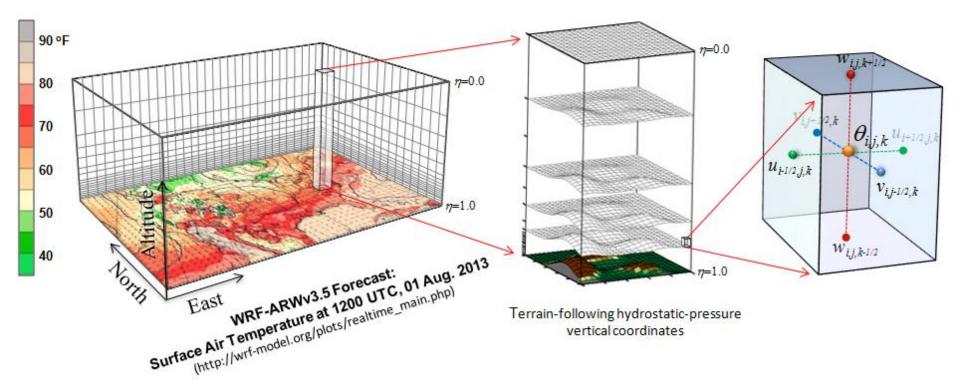
- Observations
- Previous model output
- A blending of observations and model output
- Here is an example of atmospheric temperature locations



How to fill the gaps?

Sides of the Box

- Energy, mass, and water flow through the sides of the box and one must provide this information to the model running inside the box
- Typically, a global model or a larger-area regional model is used to supply this information across the lateral boundaries

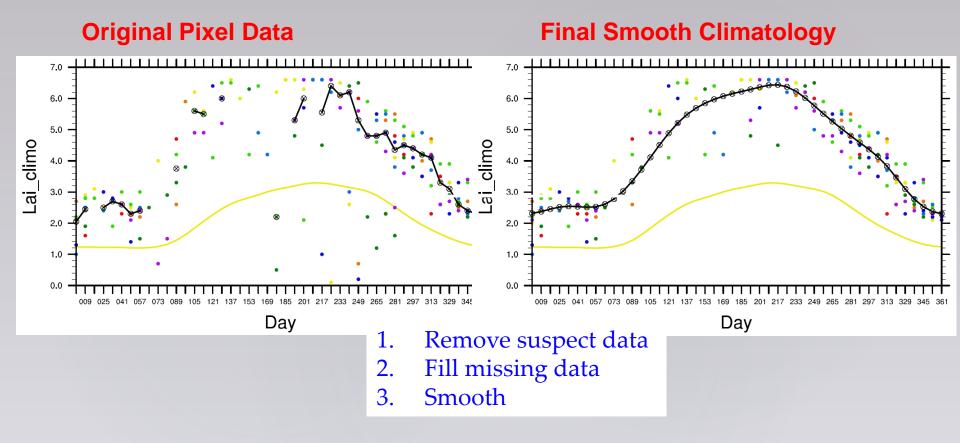


Parameterization

- What about the sub-grid scale?
- This is where one must use (physically-based) statistical relations to "parameterize" what is happening.
- What is parameterized?
 - Clouds Microphysics Precipitation
 - Convection
 - Radiation
 - Boundary Layer
 - Land Surface plants, soil, snow
- The land surface in important for forecasts of all time scales. Why?
 - Memory significant sources exist in soil (water and energy), snow and vegetation

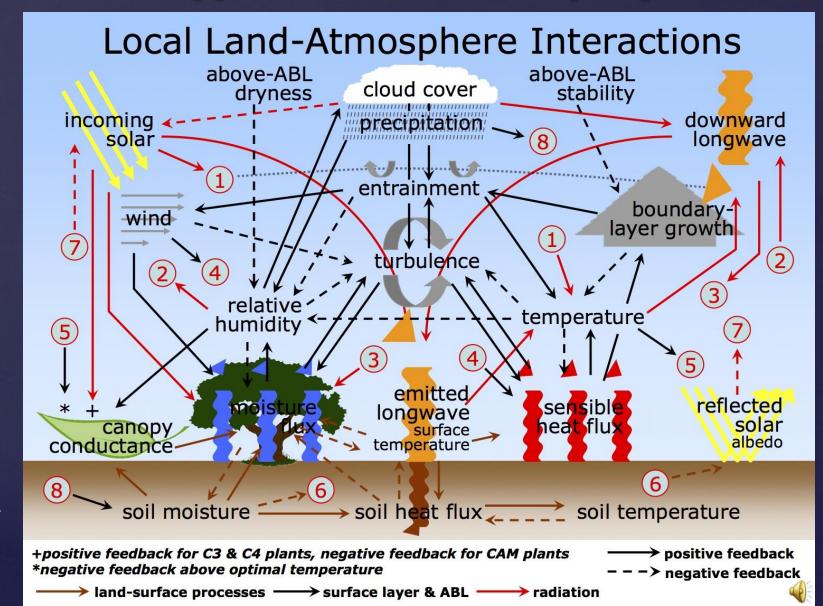
Challenge: parameter specification

Parameter Uncertainty: Vegetation





The Bottom Boundary Where it all happens (land modeler's perspective)



Courtesy Mike Ek (NOAA)

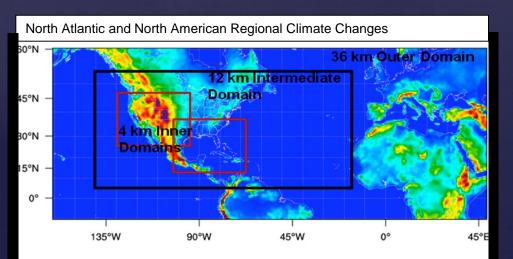
Parameterization

- Land surface modeling is moving beyond just being a source of energy and water fluxes to the atmosphere
- Land surface models now focus on a more process-based approach instead of a bulk representation
- Land surface models can now produce detailed surface states
 - Vegetation temperature
 - Soil layer temperature and moisture
 - Snow depth and water
 - Vegetation, including crop, growth
 - Upper soil aquifer interactions

Weather Research and Forecasting (WRF) Model

Widely-used "community model" for both research and operational forecasting

- Academic scientists
- Forecast teams at operational centers
- Applications communities (e.g. Air Quality, Agriculture, Hydrology, regional climate, Utilities)





Registered Users 1/1/14

American universities, Govt. labs, Private sector 6782

Foreign users

14775

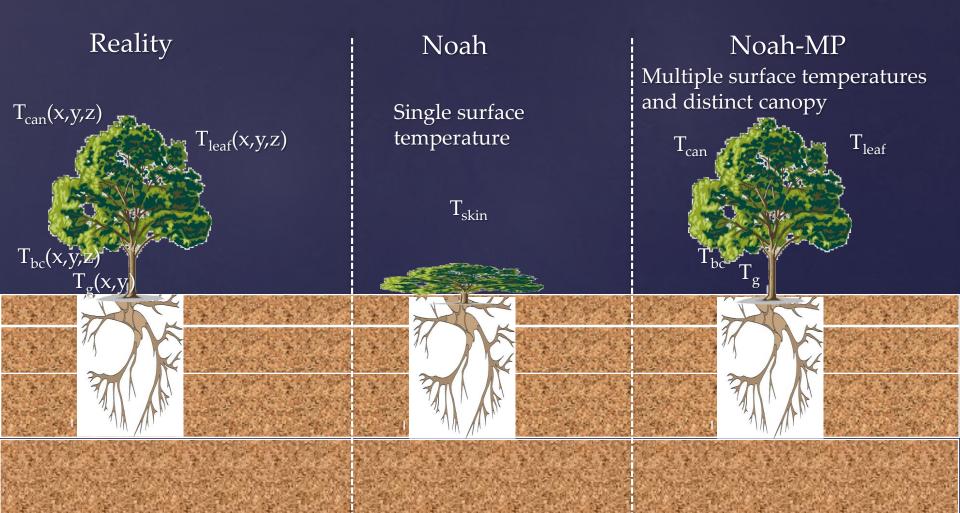
21557

Countries represented: 152

Model Uncertainty: Land Surface Model Structure

Noah LSM in NOAA Eta, NAM, GFS, CFS, MM5 and WRF Models (Pan and Mahrt 1987, Chen et al. 1996, Chen and Dudhia 2001, Ek et al., 2003)

Noah-MP LSM in WRF and NOAA GFS (Yang et al., 2011; Niu et al., 2011)



Noah-MP: a community land model Parameterization -> sub-grid -> uncertainty

JOURNAL OF GEOPHYSICAL RESEARCH, VOL. 116, D12109, doi:10.1029/2010JD015139, 2011

The community Noah land surface model with multiparameterization options (Noah-MP): 1. Model description and evaluation with local-scale measurements

Guo-Yue Niu,^{1,2} Zong-Liang Yang,¹ Kenneth E. Mitchell,³ Fei Chen,⁴ Michael B. Ek,³ Michael Barlage,⁴ Anil Kumar,⁵ Kevin Manning,⁴ Dev Niyogi,⁶ Enrique Rosero,^{1,7} Mukul Tewari,⁴ and Youlong Xia³

Received 4 October 2010; revised 3 February 2011; accepted 27 March 2011; published 24 June 2011.

The community Noah land surface model with multiparameterization options (Noah-MP):

2. Evaluation over global river basins

Zong-Liang Yang,¹ Guo-Yue Niu,^{1,2} Kenneth E. Mitchell,³ Fei Chen,⁴ Michael B. Ek,³ Michael Barlage,⁴ Laurent Longuevergne,⁵ Kevin Manning,⁴ Dev Niyogi,⁶ Mukul Tewari,⁴ and Youlong Xia³

Received 4 October 2010; revised 4 February 2011; accepted 25 March 2011; published 24 June 2011.

Noah-MP: a community land model

- Multiple parameterizations to treat key hydrologysnow-vegetation processes in a single land modeling framework
- In a broad sense,
 - Multi-physics = Multi-hypothesis
- A modular & powerful framework for
 - Diagnosing differences in process representation
 - Identifying structural errors
 - Improving understanding of physical processes
 - Enhancing data/model fusion and data assimilation
 - Facilitating ensemble forecasts and uncertainty quantification

Noah-MP: a community land model

- 1. Leaf area index (prescribed; predicted)
- 2. Turbulent transfer (Noah; NCAR LSM)
- 3. Soil moisture stress factor for transpiration (Noah; SSiB; CLM)
- 4. Canopy stomatal resistance (Jarvis; Ball-Berry)
- 5. Snow surface albedo (BATS; CLASS)
- 6. Frozen soil permeability (Noah; Niu and Yang, 2006)
- 7. Supercooled liquid water (Noah; Niu and Yang, 2006)
- 8. Radiation transfer:
 - Modified two-stream: Gap = $f(3D \text{ structure}; \text{ solar zenith angle}; ...) \leq 1\text{-}GVF$ Two-stream applied to the entire grid cell: Gap = 0 Two-stream applied to fractional vegetated area: Gap = 1-GVF
- 9. Partitioning of precipitation to snowfall and rainfall (CLM; Noah)
- 10. Runoff and groundwater:
 - TOPMODEL with groundwater
 - TOPMODEL with an equilibrium water table (Chen&Kumar,2001)
 - Original Noah scheme
 - BATS surface runoff and free drainage
- More to be added

North American Regional Climate Simulations with WRF/Noah-MP: Validation and the effect of groundwater interaction

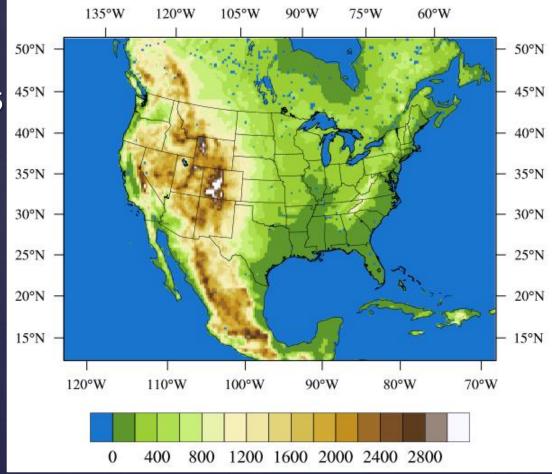
Michael Barlage

Mukul Tewari, Fei Chen, Kevin Manning (NCAR) Gonzalo Miguez-Macho (U. Santiago)

14th WRF Users' Workshop

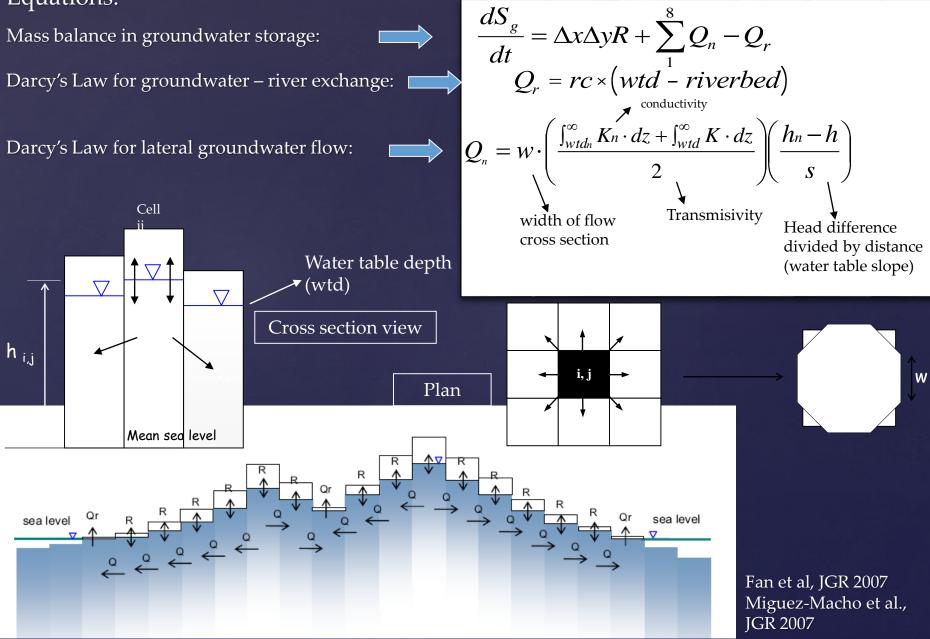
Domain and Setup

- Two six-month 30km simulations starting Feb 25
- 2002 and 2010
- Spin-up soil for one year using offline HRLDAS
- IC/BC from NARR
- CAM radiation; YSU; Thompson

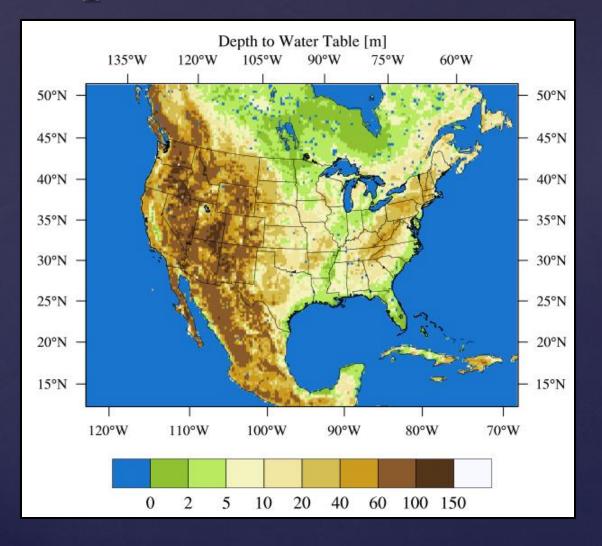


Miguez-Macho & Fan water table dynamics in Noah-MP





Depth to Water Table

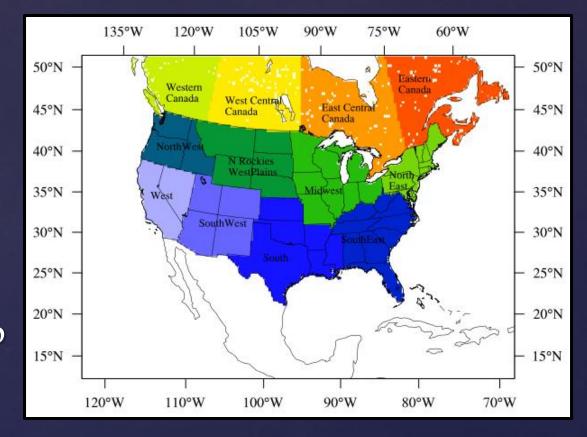


Looks similar to terrain

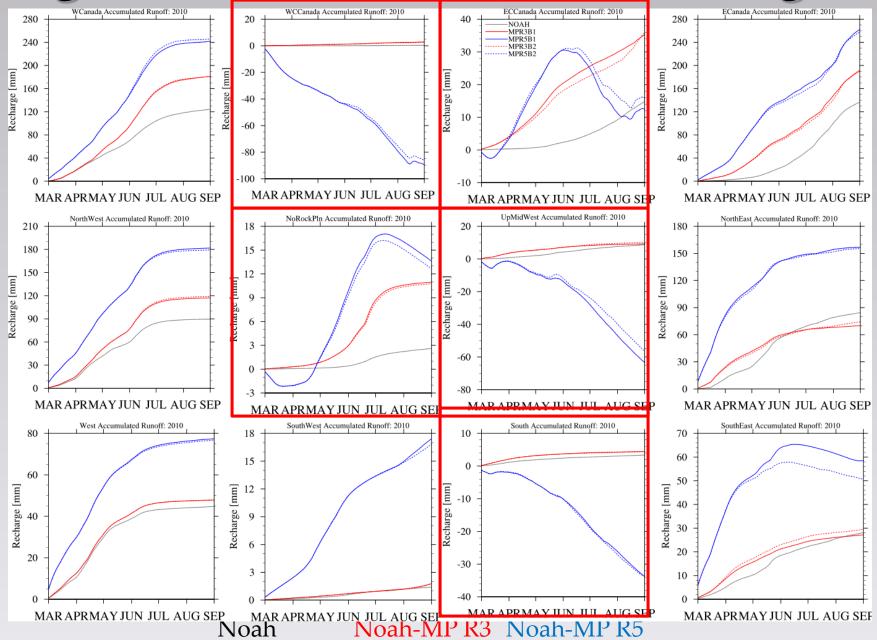
Focus of this presentation are locations with shallow water table

Analysis Regions

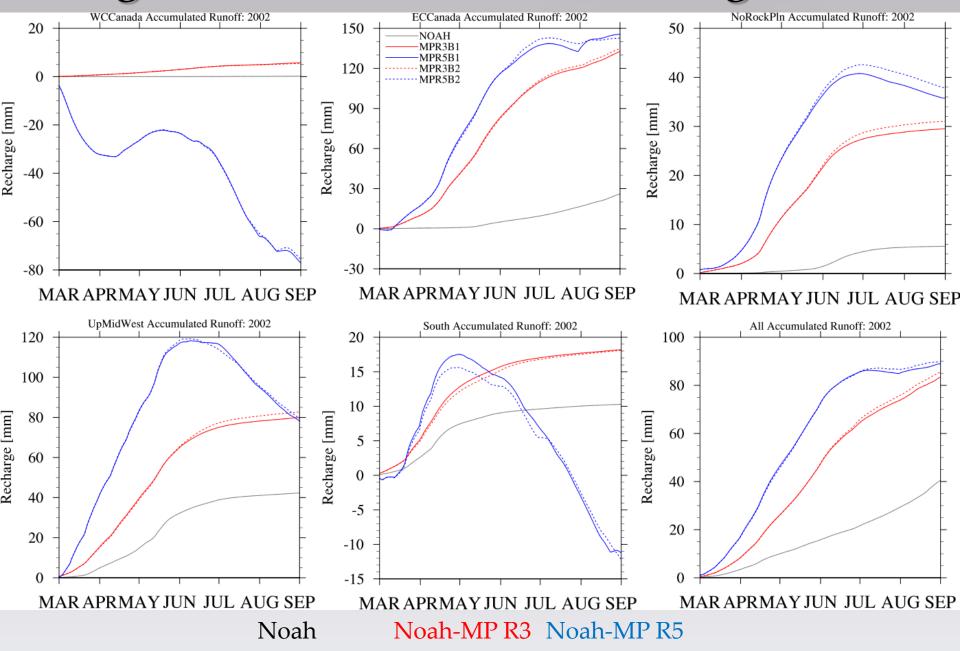
- Based on NCDC Regional Climate Zones
- Observations: METAR/SYNOP stations, NCDC daily gridded precip



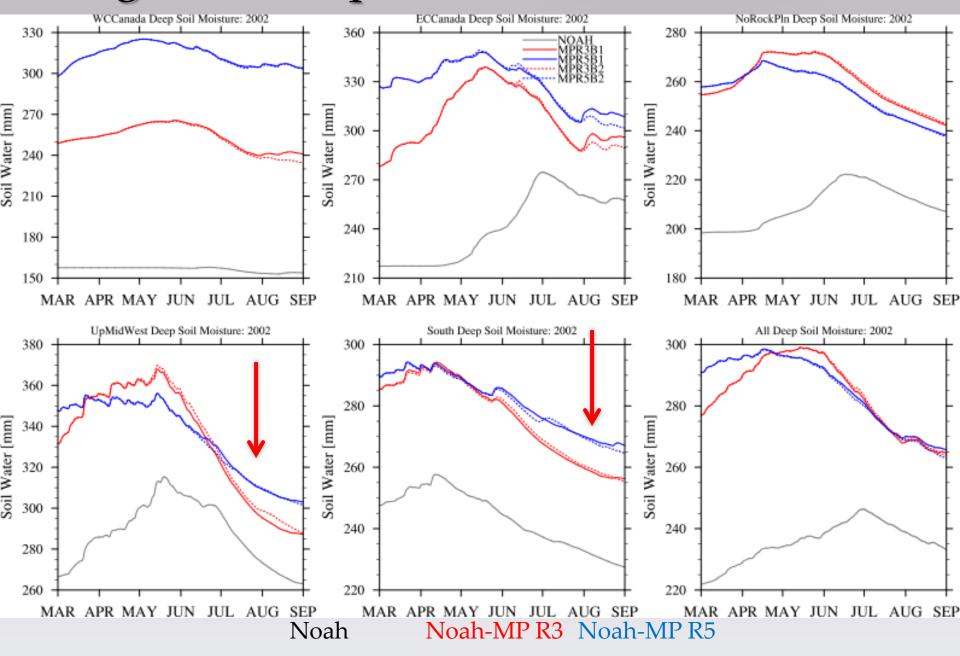
Regional Groundwater Recharge



Regional Groundwater Recharge: 2002



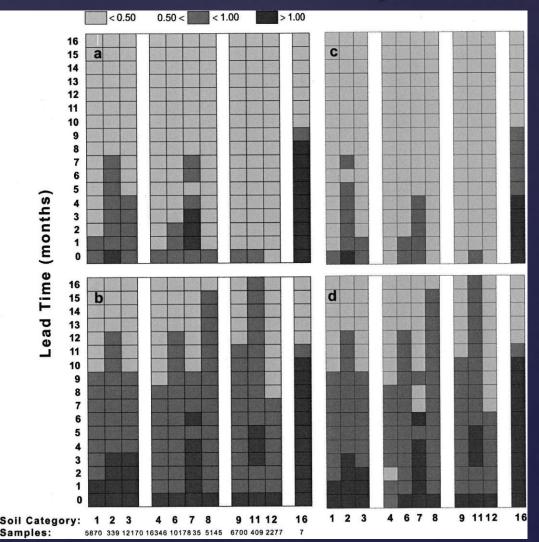
Regional Deep Soil Moisture: 2002



Initialization Uncertainty Importance of Initialization Consistency

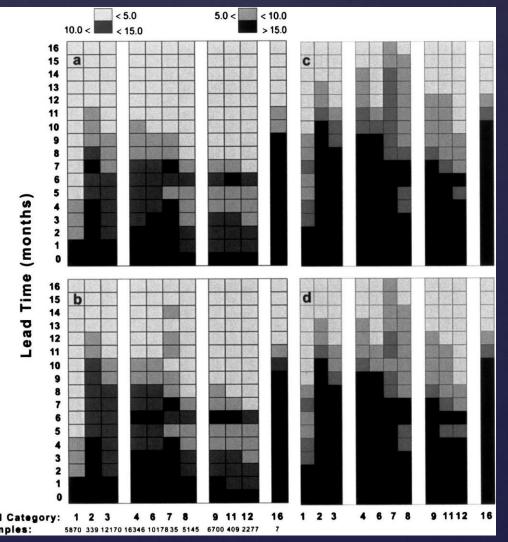
Soil

- Before running a model, significant spin-up is required to ensure initialization consistency
- For soil temperature, this can require a year or more

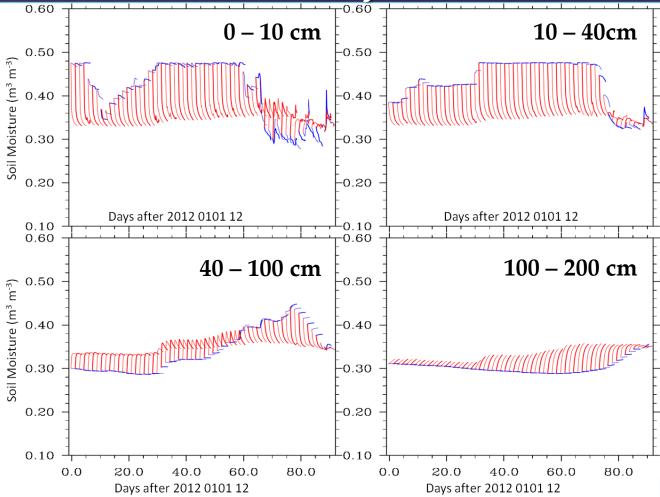


Initialization Uncertainty Importance of Initialization Consistency

- Before running a model, significant
 spin-up is required to ensure initialization
 consistency
- For surface fluxes, this can require even more time

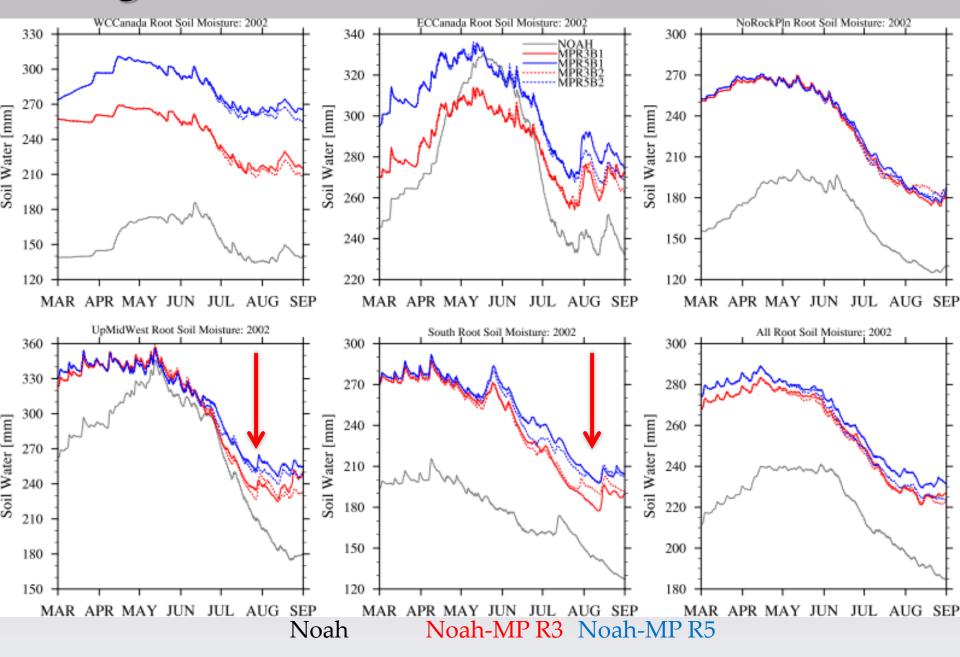


Initialization Uncertainty Importance of Initialization Consistency Soil Moisture by Level

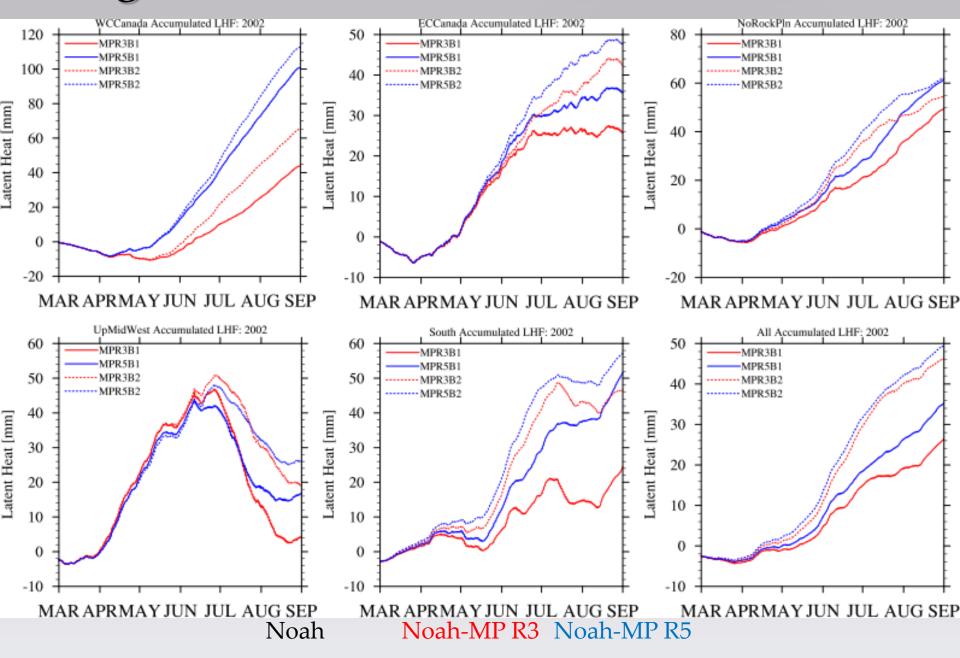


Noah in blue Noah-MP in red

Regional Root Soil Moisture: 2002

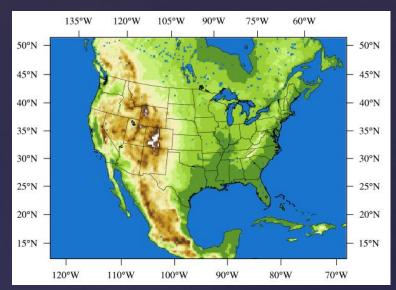


Regional Latent Heat Flux: 2002



Noah vs. NoahMP Surface Verification

- Six-month 30km WRF simulations 2010
- Spin-up soil for one year using offline HRLDAS
- IC/BC from NARR
- Verification against ~2600 surface stations



Model	Season	Output field	Day bias	Day RMSE	Night bias	Night RMSE
Noah	MAM	T_{2m}	-2.79	3.18	-1.95	2.17
Noah-MP	MAM	T_{2m}	0.17	0.92	-0.01	0.77
Noah	JJA	T_{2m}	-0.04	0.75	-1.04	1.37
Noah-MP	JJA	T_{2m}	1.09	1.53	0.13	0.94
Noah	MAM	Td _{2m}	-0.48	1.16	-1.29	1.64
Noah-MP	MAM	Td _{2m}	0.19	1.04	0.48	1.01
Noah	JJA	Td _{2m}	-0.98	1.53	-1.73	2.08
Noah-MP	JJA	Td _{2m}	-1.18	1.84	-1.00	1.57

Green: Noah-MP improves Red: Noah-MP degrades

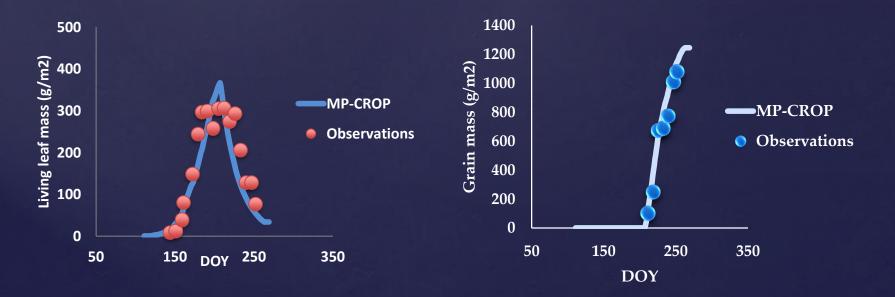
Development of WRF-Crop

- Built upon the WRF-Hydro and Noah-MP ensemble modeling framework
- Extend the dynamic vegetation model in Noah-MP to parameterize crop yield
 - Noah-MP photosynthesis-based dynamic vegetation allocates carbon to leaves, stems, grain, roots and wood as well as fast and slow soil carbon pools
 - Incorporate a whole suite of crop growth modules (rice, corn, wheat, sorghum, soybean, etc.)
- Extend WRF-Hydro to parameterize irrigation
 - A groundwater transfer and storage with dynamic water table depth
 - Aquifer water recharges lowest soil layers and can also added to surface water as irrigation

Development of WRF-Crop

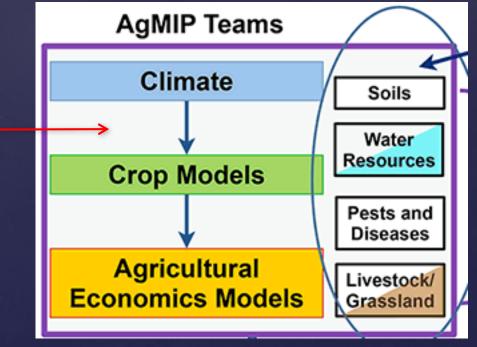


Noah-MP predicted green leaf mass (left) and grain mass (right) at an Illinois site (corn)



Model Intercomparison

- Land modelers like to do "intercomparison projects"
- This is essentially a method of "fair" performance evaluation.
- Yield modelers like to do this too: the Agricultural Model Intercomparison Project



Rosenzweig et al. 2013

Note the lack of two-way interaction

NARCCAP

North American Regional Climate Change Assessment Program

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 - Access Data User Directory Contributions Acknowledgements

RESULTS

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- General Results NCEP-Driven RCM Runs
- Climate Change Results

 CRCM+CCSM
 CRCM+CGCM3
 ECP2+GFDL
 HRM3+GFDL
 HRM3+HadCM3
 MM5I+CCSM
 MM5I+HadCM3 NEW!
 RCM3+CGCM3
 RCM3+GFDL
 WRFG+CCSM
 WRFG+CGCM3

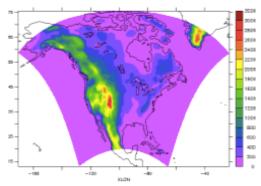
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About NARCCAP

About the Program

The North American Regional Climate Change Assessment Program (NARCCAP) is an international program to produce high resolution climate change simulations in order to investigate uncertainties in regional scale projections of future climate and generate climate change scenarios for use in impacts research.



NARCCAP modelers are running a set of

regional climate models (RCMs) driven by a set of atmosphere-ocean general circulation models (AOGCMs) over a domain covering the conterminous United States and most of Canada.

The AOGCMs have been forced with the SRES A2 emissions scenario for the 21st century. Simulations with these models were also produced for the current (historical) period. The RCMs are nested within the AOGCMs for the current period 1971-2000 and for the future period 2041-2070. As a preliminary step to evaluate the performance of the RCMs over North America, the RCMS are driven with NCEP Reanalysis II data for the period 1979-2004. All the RCMs are run at a spatial resolution of 50 km.

RCM Characteristics — AOGCM Characteristics — RCM/GCM combinations.

NARCCAP also includes two timeslice experiments at 50 km resolution using the GFDL atmospheric model (AM2.1) and the NCAR CCSM atmospheric model (CAM3). In a timeslice experiment, the atmospheric component of an AOGCM is run using observed sea surface temperatures and sea ice boundaries for the historical run, and those same observations combined with perturbations from the future AOGCM for the scenario run. Omitting the coupled ocean model saves considerable computation and allows the atmospheric model to be run at higher resolution.

Thoughts

- Regional climate models contain many sources of uncertainty
- We need to be able to assess and communicate the effect of these uncertainties on model output
- A good start is with ensemble multi-model, and perturbed parameter and initialization approaches
- Tools are being developed to address this (e.g., multi-model models)
- What information is useful?